#### **RFID SysTech'07**

Design and Analysis of a Complete RFID System in the UHF Band Focused on the Backscattering Communication and Reader Architecture

> I. Mayordomo, A. Ubarretxena, D. Valderas, R. Berenguer, Í. Gutiérrez







#### Contents

- 1. Introduction
- 2. Goals
- 3. Tag Model
- 4. Channel Model
- 5. Reader Architecture
- 6. Simulation Results
- 7. Conclusions





## **1. Introduction**







## Introduction (I)

- Passive RFID Systems:
  - Lower size, lower cost, higher lifetime.
- UHF bands:
  - 860-960 MHz and 2.45 GHz ISM Bands
  - Higher data-rates, longer distances.
- Trade-off:
  - Antenna Size vs Reading distance.
  - 868 MHz (Longer distance preferable)
- Normative:
  - EPCGlobal UHF Class 1 Generation 2
  - EN 302 208-1



## Introduction (II)

- Reader-to-tag Communication: ASK
- Tag-to-reader Communication: ASK, PSK
  - Backscattering







## 2. Goals









- State of the art:
  - Guidelines and results from the tag point of view.
  - Little information about long range RFID reader design.
- Complete long range passive RFID system design and analysis.
- Compliant with the EPCGlobal UHF Class 1 Generation 2 standard and European regulations.
- Focused on reader architecture and backscattering tag-to-reader communication.
- Main objective: maximize operating distance.





# 3. Tag model







## Tag model (I): Backscattering

- Energy reaching the tag:
  - Part is used for supply
  - Part is backscattered
- Changes in reflection coefficient
  - Resistance: ASK modulation
  - Reactance: PSK modulation (longer distances)



$$\theta = -\arctan\left(\frac{R_A X}{R_A^2 + 2X^2}\right)$$
$$P_{BS} = P_{AV} \frac{4\left(R_A^2 + X^2\right)}{R_A^2 + 4X^2}$$

[1] G. De Vita and G. Iannaccone, "Design Criteria for the RF section of UHF and Microwave passive RFID transponders" IEEE Trans. Microw. Theroy Tech., vol. 53, no.9, pp. 2985-2989, Sep. 2005



## Tag Model (II)

- Backscattered power must remain constant
- A series of equations developed to work out L and C in order to cause a predefined dephase in the backscattered signal.







## 4. Channel Model







## **Propagation Channel**

- Signal crosses the channel twice
- Free Space Losses:



- Additive White Gaussian Noise (AWGN)
- Random Phase Shift





## 5. Reader Architecture







#### **Reader Architecture**





#### Power received at the reader

- Polarization considerations:
  - Tag antenna: linear
  - Tag position: arbitrary
  - Reader antenna transmits circular:
    - 3dB Losses due to polarization mismatch
- Friis Formula:

$$P_{R} = P_{T}G_{tag}^{2}G_{reader}^{2} \frac{4(R_{A}^{2} + X^{2})}{R_{A}^{2} + 4X^{2}} p\left(\frac{\lambda}{4\pi d}\right)^{4}$$



### **Transmission Leakage**

- The reader transmits and receive at the same time and in the same frequency.
- Reader radiated power: 2 W e.r.p. (33 dBm)
  - Circulator isolations around 30 dB
- Backscattered signal masked
- Very high dynamic range required, RF stage can get saturated (mixer)
- DC Offsets at baseband due to self-mixing
  - Coupling stage necessary



## **Output switching circuitry**

- 2 Options for simultaneous Tx/Rx:
  - Circulator (isolation provided by circulator)
  - -2 Antennas (external isolation)
- Both can be combined:





#### **Quadrature downconversion**

- Phase shift introduced by the channel.
  Modulation is not affected but…
- Coherent detection is not realizable.
- I/Q Demodulation necessary:
  - When one channel is at maximum sensitivity, the other is at minimum.
- Two options:
  - Parallel processing
  - I and Q Paths combination



#### Demodulation

$$i(t) = \sum_{m=0}^{\infty} A \operatorname{Re} ct \left( \frac{t - T/4 - mT/2}{T/2} \right) \cos\left(\theta_m + \beta + \phi(t)\right) + n(t)$$

$$q(t) = \sum_{m=0}^{\infty} A \operatorname{Re} ct \left( \frac{t - T/4 - mT/2}{T/2} \right) \sin(\theta_m + \beta + \phi(t)) + n(t)$$







## 6. Simulation Results







### **Simulation results**

- Study of the parameters that mainly affect reading distance.
- A complete passive RFID system simulation environment has been developed in ADS.
- Reader architecture is simulated with real commercial components.
- Maximum reading distance from the reader point of view.
  - Maximum BER at the reader  $(10^{-3})$ .



#### **Tag Phase Variation**

Typical phase variations: 5°- 15°



Tag Dephase (°)



## Data Rate (FM0 Encoding)

Date rates allowed by the standard:
– From 40 Kbps to 640 Kbps





#### **Circulator Isolation**

Commercial circulators: ~30 dB Isolation
A 60 dB isolation circulator reported



Isolation (dB)



#### **Phase Noise**

Commercial oscillator phase noise (dBc/Hz):
- 92@1kHz, -116@100kHz, -138@1MHz, -144@3MHz







## 7. Conclusions







#### Conclusions

- A complete long range passive RFID system has been designed and analyzed.
- Guidelines for a proper long range passive RFID reader are derived.
- The tag is not the only limiting factor in a passive RFID system.
- Tx/Rx Isolation and Phase noise are reader key design issues.





#### Thank you for your attention. Questions and comments are welcome.

#### Iker Mayordomo Contact: imayordomo@tecnun.es





